

Optimal Control

Course Workload		Assessment form (examination/ graded test/ ungraded test)
ECTS	Hours	
3	108	Ungraded test

Discipline deals with optimal control design for a dynamical systems or plants, that described by differential equations.

Course structure:

1. Static optimization

- 1.1. Method of Lagrange multipliers
- 1.2. Methods of static optimization
- 1.3. Kuhn–Tucker conditions
- 1.4. Necessary and sufficient conditions for function extrema

2. Optimal control problem statement

- 2.1. The problem of optimal control. Formulation. Examples
- 2.2. Classical cost function in the Lagrange, Bolza, and Mayer forms
- 2.3. The definitions of the Lagrangian and Hamiltonian

3. Variation Calculus

- 3.1. Euler–Lagrange equation
- 3.2. Linear quadratic regulator

4. Pontryagin's maximum principle

- 4.1. Legendre condition
- 4.2. Transversality conditions
- 4.3. The problem with free state points and fixed time
- 4.4. The problems with fixed state and time points

5. Dynamic programming

- 5.1. Optimal Control of a Discrete System
- 5.2. Bellman's Principle of Optimality
- 5.3. Hamilton-Jacobi-Bellman Equation

6. Kalman filter

6.1. Optimal State Estimation

6.2. Kalman-Bucy Filter